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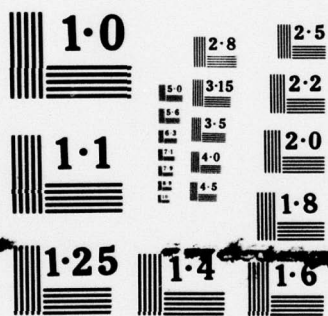
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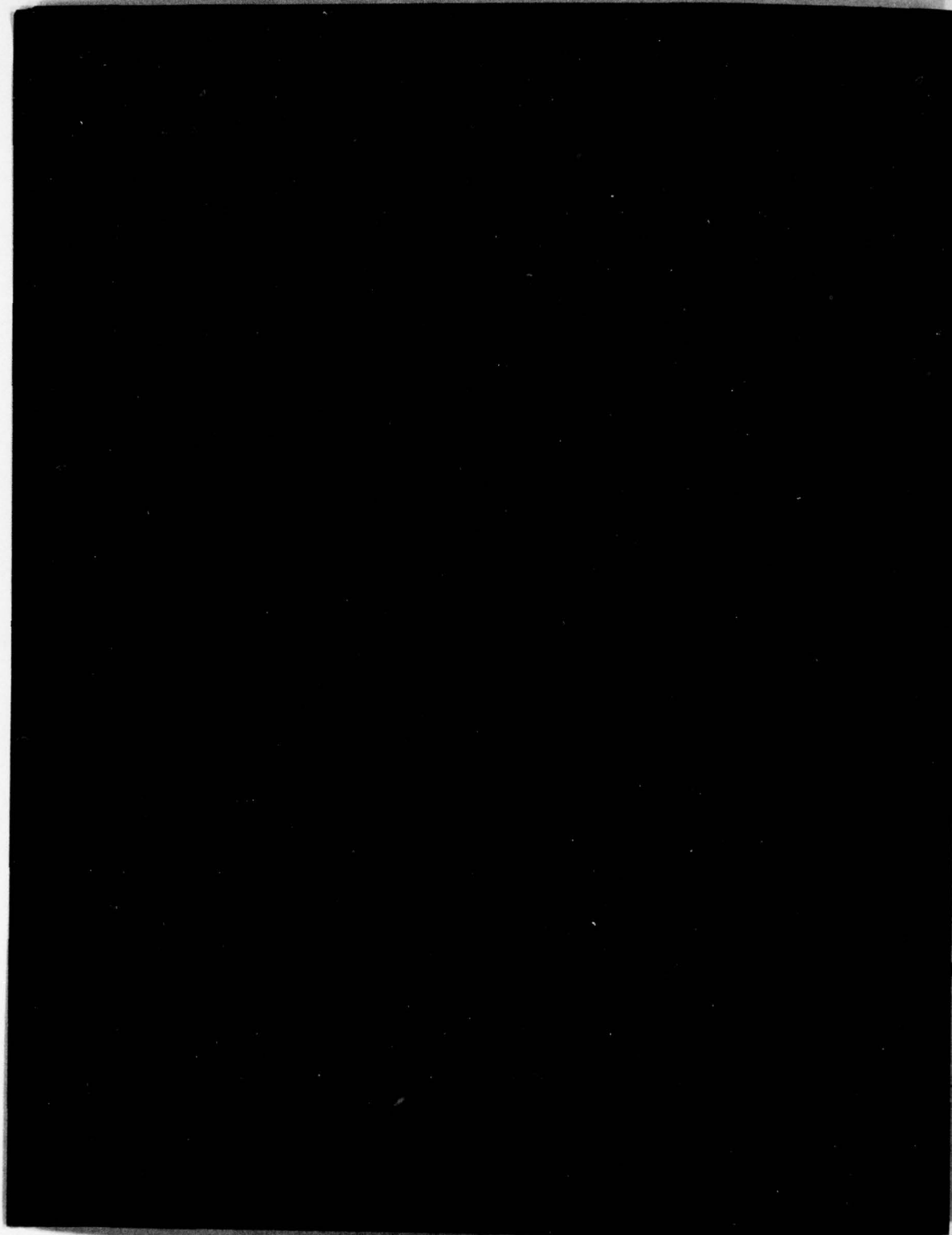
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modes--are determined, and the associated fields are plotted. One higher order mode--the TM_2 -like mode propagating at an angle of 19 deg with respect to one of the principal axes--also is plotted. These results relate to the problem of the interaction of sheet laser beams with surface acoustic waves.



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1. INTRODUCTION

In surface acoustic wave (SAW) devices, the interaction between laser beams and acoustic waves must be understood by considering the allowed surface modes of both disturbances. In this report, the formalism for determining the modes for electromagnetic (laser) waves is reviewed and solved for propagation in an anisotropic dielectric slab. It is shown that pure transverse electric (TE) and transverse magnetic (TM) modes are possible only if propagation occurs parallel to the principal axes of the material, but that coupled TE- and TM-like modes occur for propagation at small angles with respect to these axes.

In section 2, the formalism is given for determining the modes for propagation at an angle with respect to one principal axis (y') of the material and parallel to another (x').

In section 3, results are obtained specifically for 0.53- μm radiation (doubled 1.06- μm radiation from a neodymium:yttrium aluminum garnet (Nd:YAG) laser) in lithium niobate (LiNbO_3). There, TE- and TM-like modes are obtained for various thicknesses of a slab backed on one face by a perfect conductor and on the other by free space. For some typical examples, the Poynting vector, S_y , indicating the magnitude of power flow, is plotted versus distance into the slab from the surface to indicate the concentration of the power. It is expected that these data when correlated with similar calculations for the SAW's will determine more precisely the regions where the interaction is strongest. These results will help clarify the dependence of the observed phenomena on polarization and the angle of propagation. Computer programs have been written to perform these calculations for the general case.

2. THEORY

In the cgs system of units, Maxwell's equations in the absence of sources are

$$\nabla \times \mathbf{E} = - \frac{1}{c} \frac{\partial \mathbf{B}}{\partial t} , \quad (1a)$$

$$\nabla \times \mathbf{H} = \frac{1}{c} \frac{\partial \mathbf{D}}{\partial t} , \quad (1b)$$

where

$$\mathbf{B} = \mu \mathbf{H} , \quad (2a)$$

$$\mathbf{D} = \epsilon \mathbf{E} , \quad (2b)$$

and μ , the permeability, and ϵ , the dielectric constant, may be tensors. Considering the quantities E , B , H , and D as column vectors, ∇X , μ , and ϵ as tensors, and $\nabla \cdot$ as a row vector, we have, for example,

$$\nabla \cdot = \left(\frac{\partial}{\partial x} \quad \frac{\partial}{\partial y} \quad \frac{\partial}{\partial z} \right) \quad (3)$$

and

$$\nabla X = \begin{bmatrix} 0 & -\frac{\partial}{\partial z} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} & 0 & -\frac{\partial}{\partial x} \\ -\frac{\partial}{\partial y} & \frac{\partial}{\partial x} & 0 \end{bmatrix} \quad (4)$$

Thus, one may easily see that the product of $\nabla \cdot$ and ∇X gives

$$\nabla \cdot (\nabla X) = \begin{pmatrix} d_{yz}^2 & d_{zx}^2 & d_{xy}^2 \end{pmatrix}, \quad (5)$$

where

$$d_{yz}^2 = \frac{\partial^2}{\partial y \partial z} - \frac{\partial^2}{\partial z \partial y} \quad (6)$$

and similarly for d_{zx}^2 and d_{xy}^2 . Assuming that the functions (column vectors) that are to be operated on by $\nabla \cdot (\nabla X)$ are well behaved, the partial derivatives may be interchanged and

$$\nabla \cdot (\nabla X) = 0. \quad (7)$$

Operating with $\nabla \cdot$ on equations (1a) and (1b), one obtains

$$\nabla \cdot B = \nabla \cdot D = 0 \quad (8)$$

as a natural consequence of Maxwell's equations with no sources.

To solve Maxwell's equations as a superposition of plane waves of the form

$$\exp(ik \cdot r - i\omega t), \quad (9)$$

equations (1a) and (1b) become

$$kXE = k_0 \mu H, \quad (10a)$$

$$kXH = -k_0 \epsilon E, \quad (10b)$$

where

$$k_0 = \omega/c, \quad (11)$$

ω is the angular frequency, and c is the velocity of light.

The most general equation for E becomes

$$UE = 0, \quad (12)$$

where

$$U = (kX)\mu^{-1}(kX) + k_0^2 \epsilon. \quad (13)$$

Analogous to equation (4),

$$kX = \begin{bmatrix} 0 & -k_z & k_y \\ k_z & 0 & -k_x \\ -k_y & k_x & 0 \end{bmatrix}. \quad (14)$$

Since equation (12) represents a set of three homogeneous equations in the E_x , E_y , and E_z components of E , solutions are obtained when the determinant of coefficients vanishes,

$$\det(U) = 0. \quad (15)$$

In this report, we consider only the case where μ is a scalar and equation (15) becomes (multiplying through by μ)

$$\det[(kX)(kX) + k_0^2 \mu \epsilon] = 0, \quad (16)$$

where from equation (14) one obtains

$$(kX)(kX) = \begin{bmatrix} -(k_y^2 + k_z^2) & k_x k_y & k_z k_x \\ k_x k_y & -(k_z^2 + k_x^2) & k_y k_z \\ k_z k_x & k_y k_z & -(k_x^2 + k_y^2) \end{bmatrix}. \quad (17)$$

The determinant given by equation (16) gives relationships among the components k_x , k_y , and k_z of k and ω (through k_o) in the medium, and any boundary conditions will further limit their allowed values. Once values for the components of k are known, then all the components of E and H may be solved in terms of any one of them by equations (1a) and (1b).

Taking the tensor components of ϵ to be ϵ_{ij} , where $\epsilon_{ij} = \epsilon_{ji}$, then equation (16) gives

$$\begin{aligned} & \left[-\left(k_y^2 + k_z^2\right) + k_o^2 \mu \epsilon_{11} \right] \left[-\left(k_z^2 + k_x^2\right) + k_o^2 \mu \epsilon_{22} \right] \left[-\left(k_x^2 + k_y^2\right) + k_o^2 \mu \epsilon_{33} \right] \\ & - \left[-\left(k_y^2 + k_z^2\right) + k_o^2 \mu \epsilon_{11} \right] \left[k_y k_z + k_o^2 \mu \epsilon_{23} \right]^2 \\ & - \left[-\left(k_z^2 + k_x^2\right) + k_o^2 \mu \epsilon_{22} \right] \left[k_z k_x + k_o^2 \mu \epsilon_{13} \right]^2 \\ & - \left[-\left(k_x^2 + k_y^2\right) + k_o^2 \mu \epsilon_{33} \right] \left[k_x k_y + k_o^2 \mu \epsilon_{12} \right]^2 \\ & + 2 \left[k_y k_z + k_o^2 \mu \epsilon_{23} \right] \left[k_z k_x + k_o^2 \mu \epsilon_{13} \right] \left[k_x k_y + k_o^2 \mu \epsilon_{12} \right] = 0. \end{aligned} \quad (18)$$

This equation gives the most general relationship between the components of k under the assumptions of an exponential space-time variation given by equation (9) and of scalar permeability μ .

We further limit the considerations in this report to no propagation in the z direction ($k_z = 0$), and $\epsilon_{12} = \epsilon_{13} = 0$.

Equation (18), where $k_z = \epsilon_{12} = \epsilon_{13} = 0$, reduces to

$$\left[-k_x^2 + k_E^2 \right] \left[-k_x^2 + k_M^2 \right] = k_{23}^4, \quad (19)$$

where

$$k_E^2 = -k_y^2 + k_o^2 \mu \epsilon_{33} \quad (\text{TE mode}), \quad (20a)$$

$$k_M^2 = \frac{\epsilon_{22}}{\epsilon_{11}} \left(-k_y^2 + k_o^2 \mu \epsilon_{11} \right) \quad (\text{TM mode}), \quad (20b)$$

$$k_{23}^4 = k_o^2 \mu \frac{\epsilon_{23}^2}{\epsilon_{11}} \left(-k_y^2 + k_o^2 \mu \epsilon_{11} \right) = \frac{k_o^2 \mu \epsilon_{23}^2}{\epsilon_{22}} k_M^2. \quad (20c)$$

The TE and TM modes exist in the limit of vanishing ϵ_{23} (resulting in a diagonal dielectric tensor). The TE mode for diagonal ϵ is a solution where $E_x = E_y = 0$; hence, $E = E_z$, which is transverse to the direction of propagation and experiences only the ϵ_{33} dielectric constant as shown in equation (20a). The TM mode for diagonal ϵ is a solution where $H_x = H_y = 0$; hence, $H = H_z$, but E lies only in the x-y plane and therefore experiences the combination of ϵ_{11} and ϵ_{22} dielectric constants shown in equation (20b).

When $\epsilon_{23} \neq 0$, as is considered below, these two modes are coupled as shown in equation (19). The specific problem that we solve is a bound wave propagating parallel to the surface of an infinite dielectric slab surfaced with a perfect conductor on one face as shown in figure 1.

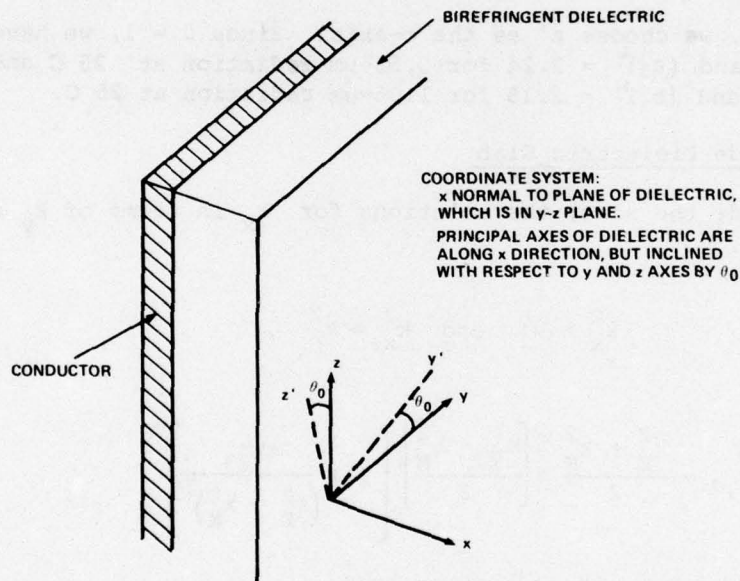


Figure 1. Representation of system to be solved for bound electromagnetic radiation propagating in x-y plane; boundaries only in x direction are considered, with slab being infinite in both y and z directions.

If the principal axes of the dielectric are parallel to the x-axis but rotated about x through an angle θ_0 as shown in figure 1, then we have

$$\epsilon_{11} = \epsilon_1 , \quad (21a)$$

$$\epsilon_{22} = \epsilon_2 \cos^2 \theta_0 + \epsilon_3 \sin^2 \theta_0 , \quad (21b)$$

$$\epsilon_{33} = \epsilon_3 \cos^2 \theta_0 + \epsilon_2 \sin^2 \theta_0 , \quad (21c)$$

$$\epsilon_{23} = (\epsilon_2 - \epsilon_3) \cos \theta_0 \sin \theta_0 , \quad (21d)$$

where ϵ_1 , ϵ_2 , and ϵ_3 are the principal dielectric constants of the material. Alternatively, we may consider $-\theta_0$ as the angle at which the electromagnetic wave is launched with respect to the ϵ_2 principal axis of the material.

In LiNbO_3 , we choose z' as the c -axis. Since $\mu = 1$, we have $(\epsilon_1)^{1/2} = (\epsilon_2)^{1/2} = 2.34$ and $(\epsilon_3)^{1/2} = 2.24$ for $0.53\text{-}\mu\text{m}$ radiation at 25 C and $(\epsilon_1)^{1/2} = (\epsilon_2)^{1/2} = 2.24$ and $(\epsilon_3)^{1/2} = 2.15$ for $1.06\text{-}\mu\text{m}$ radiation at 25 C.

2.1 Inside Dielectric Slab

Inside the slab, the solutions for k_x in terms of k_y are, from equation (19),

$$k_x^2 = k_1^2 \quad \text{and} \quad k_x^2 = k_2^2 , \quad (22a)$$

where

$$k_{1,2}^2 = \frac{k_E^2 + k_M^2}{2} \pm \left[\frac{k_E^2 - k_M^2}{2} \right] \left[1 + \frac{4k_{23}^4}{(k_E^2 - k_M^2)^2} \right]^{1/2} \quad (22b)$$

and where k_E^2 , k_M^2 , and k_{23}^4 are given in terms of k_y by equations (20a, b, c), respectively. From equations (1a) and (1b), one has

$$\frac{\partial}{\partial y} E_z = ik_0 \mu H_x , \quad (23a)$$

$$-\frac{\partial}{\partial x} E_z = ik_0 \mu H_y , \quad (23b)$$

$$\frac{\partial}{\partial x} E_y - \frac{\partial}{\partial y} E_x = ik_0 \mu H_z , \quad (23c)$$

$$\frac{\partial}{\partial y} H_z = -ik_0 \epsilon_{11} E_x, \quad (23d)$$

$$-\frac{\partial}{\partial x} H_z = -ik_0 (\epsilon_{22} E_y + \epsilon_{23} E_z), \quad (23e)$$

$$\frac{\partial}{\partial x} H_y - \frac{\partial}{\partial y} H_x = -ik_0 (\epsilon_{23} E_y + \epsilon_{33} E_z). \quad (23f)$$

The arbitrary solution in the slab is a linear combination of sines and cosines of $k_1 x$ and $k_2 x$. For convenience, we define coefficients u_1 , u_2 , u_3 , and u_4 such that

$$E_z = (u_1 + u_2 t_1) \cos k_1 x + \epsilon_{23} (u_3 + u_4 t_2) \cos k_2 x, \quad (24a)$$

where

$$t_{1,2} = \tan k_{1,2} x / k_{1,2}. \quad (24b)$$

From equation (23a),

$$H_x = k_y E_z / (\mu k_0). \quad (24c)$$

From equation (23b), one has

$$H_y = -i [(u_1 t_1 k_1^2 - u_2) \cos k_1 x + \epsilon_{23} (u_3 t_2 k_2^2 - u_4) \cos k_2 x] / (\mu k_0). \quad (24d)$$

From equation (23f), one has

$$E_y = \left[\frac{(k_1^2 - k_E^2)}{\epsilon_{23}} (u_1 + u_2 t_1) \cos k_1 x + (k_2^2 - k_E^2) (u_3 + u_4 t_2) \cos k_2 x \right] / (\mu k_0^2). \quad (24e)$$

From equations (23c, d) and (24e),

$$H_z = i\epsilon_{22} \left[\frac{(k_1^2 - k_E^2)}{\epsilon_{23}} (u_1 t_1 k_1^2 - u_2) \cos k_1 x + (k_2^2 - k_E^2) (u_3 t_2 k_2^2 - u_4) \cos k_2 x \right] / (\mu k_O k_M^2) \quad (24f)$$

Finally, from equations (23d) and (24f),

$$E_x = -k_y H_z / (\epsilon_{11} k_O) \quad (24g)$$

Thus, equations (24a) to (24g) give the six components of E and H in terms of the arbitrary constants u_1 , u_2 , u_3 , and u_4 , which are to be determined by the boundary conditions up to a constant factor.

2.2 Outside Dielectric Slab

Outside the dielectric slab, we have, in addition to the previously assigned conditions, $\epsilon_{11} = \epsilon_{22} = \epsilon_{33} = \mu = 1$ and $\epsilon_{23} = 0$. From equations (20a, b, c), which apply since they are perfectly general, $k_{23}^4 = 0$; and the solutions of equation (19) split into the TE and TM modes, which give the same solution, that is,

$$k_x^2 = -k_y^2 + k_O^2 \quad (25)$$

We are interested in a bound wave, so we choose

$$k_x = i\Gamma \quad (26)$$

so that

$$\Gamma^2 = k_y^2 - k_O^2 \quad (27)$$

and we look for solutions for positive Γ . The choice of sign given by equation (26) gives x variations of the form

$$e^{-\Gamma x} \quad (28)$$

which die in the positive x direction as shown in figure 1 if Γ is positive.

The spatial solution outside the slab may be written for E_z as

$$E_z = -u_5 e^{-\Gamma x} e^{ik_y y} . \quad (29a)$$

Following the procedure for solving the various equations starting from equation (23a), we have

$$H_x = \frac{k_y}{k_0} E_z , \quad (29b)$$

$$H_y = -i \frac{\Gamma}{k_0} E_z , \quad (29c)$$

$$E_y = \lim_{\epsilon_{23} \rightarrow 0} \frac{1}{k_0^2 \epsilon_{23}} \left(-k_0^2 + k_y^2 - \Gamma^2 \right) E_z . \quad (29d)$$

But since Γ^2 is related to k_y^2 according to equation (27), one gets an indeterminant form for E_y . Thus, we may define E_y better by choosing H_z to have the spatial variation

$$H_z = i u_6 e^{-\Gamma x} e^{ik_y y} / (\mu k_0) , \quad (30a)$$

and we obtain from equations (23d, e)

$$E_x = - \frac{k_y}{k_0} H_z , \quad (30b)$$

$$E_y = i \frac{\Gamma}{k_0} H_z . \quad (30c)$$

These equations are independent of, but analogous to, equations (29a, b, c).

2.3 Matching Boundary Conditions

We set E tangential and H tangential to be continuous across the dielectric-air boundary at $x = 0$, and we set E tangential zero at the metal boundary at $x = -L$, where L is the dielectric slab thickness.

From equations (24a) and (29a), we set E_z continuous at $x = 0$ to get

$$u_1 + \epsilon_{23} u_3 = -u_5 ; \quad (31a)$$

from equations (24d) and (29c), we set H_y continuous at $x = 0$ to get

$$u_2 + \epsilon_{23} u_4 = \mu \Gamma u_5 ; \quad (31b)$$

from equations (24e) and (30a, c), we set E_y continuous at $x = 0$ to get

$$(k_1^2 - k_E^2) u_1 + \epsilon_{23} (k_2^2 - k_E^2) u_3 = -\epsilon_{23} \Gamma u_6 ; \quad (31c)$$

from equations (24f) and (30a), we set H_z continuous at $x = 0$ to get

$$(k_1^2 - k_E^2) u_2 + \epsilon_{23} (k_2^2 - k_E^2) u_4 = -\frac{\epsilon_{23}}{\epsilon_{22}} k_M^2 u_6 ; \quad (31d)$$

from equation (24a), we set $E_z = 0$ at $x = -L$ to get

$$u_1 \cos k_1 L - u_2 \frac{\sin k_1 L}{k_1} + \epsilon_{23} u_3 \cos k_2 L - \epsilon_{23} u_4 \frac{\sin k_2 L}{k_2} = 0 ; \quad (31e)$$

from equation (24e), we set $E_y = 0$ at $x = -L$ to get

$$\begin{aligned} & (k_1^2 - k_E^2) \left(u_1 \cos k_1 L - u_2 \frac{\sin k_1 L}{k_1} \right) \\ & + \epsilon_{23} (k_2^2 - k_E^2) \left(u_3 \cos k_2 L - u_4 \frac{\sin k_2 L}{k_2} \right) = 0 . \end{aligned} \quad (31f)$$

For a solution, the following determinant of the coefficients must vanish:

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & -\mu\Gamma & 0 \\ k_1^2 - k_E^2 & 0 & k_2^2 - k_E^2 & 0 & 0 & \Gamma \\ 0 & k_1^2 - k_E^2 & 0 & k_2^2 - k_E^2 & 0 & k_M^2/\epsilon_{22} \\ \cos k_1 L & -\frac{\sin k_1 L}{k_1} & \cos k_2 L & -\frac{\sin k_2 L}{k_2} & 0 & 0 \\ (k_1^2 - k_E^2) \cos k_1 L & -(k_1^2 - k_E^2) \frac{\sin k_1 L}{k_1} & (k_2^2 - k_E^2) \cos k_2 L & -(k_2^2 - k_E^2) \frac{\sin k_2 L}{k_2} & 0 & 0 \end{bmatrix} = 0 \quad (32)$$

From equations (20a, b, c), (22b), and (27), each of the quantities in the determinant is expressed in terms of k_y^2 . Thus, the solution of equation (32) gives the allowed values for k_y^2 .

In the limit $\epsilon_{23} \rightarrow 0$ ($\theta_0 = 0$ for propagation perpendicular to the c-axis in LiNbO_3), equations (31a to f) split into two independent sets of three equations. In general,

$$\frac{k_1^2 - k_E^2}{\epsilon_{23}} = -\epsilon_{23} \frac{\mu k_O^2 k_M^2}{\epsilon_{22}(k_2^2 - k_E^2)} \quad (33)$$

so that, in the limit $\epsilon_{23} \rightarrow 0$,

$$k_1 \rightarrow k_E, \quad (34a)$$

$$k_2 \rightarrow k_M, \quad (34b)$$

$$\frac{k_1^2 - k_E^2}{\epsilon_{23}} \rightarrow 0. \quad (34c)$$

One solution is the TE solution obtained by striking columns 3, 4, and 6 in equation (32) and thereby getting

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & k_E & -\mu\Gamma \\ \cos k_E L & -\sin k_E L & 0 \end{bmatrix} = 0 \quad (35)$$

or

$$1 + \frac{\mu\Gamma}{k_E} \tan k_E L = 0, \quad (36)$$

with

$$\begin{aligned} k_E^2 &= k_O^2 \mu \epsilon_{33} - k_Y^2, \\ \Gamma^2 &= k_Y^2 - k_O^2. \end{aligned}$$

The second solution is the TM solution obtained by striking columns 1, 2, and 5 in equation (32) and thereby getting

$$\begin{bmatrix} 1 & 0 & \Gamma \\ 0 & 1 & k_M/\epsilon_{22} \\ \cos k_M L & -\sin k_M L & 0 \end{bmatrix} = 0 \quad (37)$$

or

$$\tan k_M L - \frac{\Gamma \epsilon_{22}}{k_M} = 0, \quad (38)$$

with

$$k_M^2 = k_O^2 \mu \epsilon_{22} - k_Y^2 \epsilon_{22} / \epsilon_{11}. \quad (39)$$

The general solutions for equation (32) are given by

$$\begin{aligned} & (k_2^2 - k_E^2) \left(1 + \mu \Gamma \frac{\tan k_1 L}{k_1} \right) \left(\frac{k_M^2}{\Gamma \epsilon_{22}} \frac{\tan k_2 L}{k_2} - 1 \right) \\ & - (k_1^2 - k_E^2) \left(1 + \mu \Gamma \frac{\tan k_2 L}{k_2} \right) \left(\frac{k_M^2}{\Gamma \epsilon_{22}} \frac{\tan k_1 L}{k_1} - 1 \right) = 0 . \quad (40) \end{aligned}$$

The second term vanishes as $\epsilon_{23} \rightarrow 0$, since $k_1^2 \rightarrow k_E^2$, and the second and third factors in the first term give, respectively, the TE and TM solutions given by equations (36) and (38) ($k_2 \rightarrow k_M$ in this limit).

2.4 Transverse Electric-like Modes

We consider cases for which θ_0 is small so that from equation (21d) $\epsilon_{23} \ll 1$. Thus, we refer to TE-like modes as those solutions of equation (40) where

$$\mu \Gamma \frac{\tan k_1 L}{k_1} \sim -1 . \quad (41)$$

For these modes, we solve for the u_i in terms of u_5 to get

$$\frac{u_6}{u_5} = \frac{k_1^2 - k_E^2}{\epsilon_{23}} \left(1 + \mu \Gamma \frac{\tan k_2 L}{k_2} \right) \left(\Gamma - \frac{k_M^2}{\epsilon_{23}} \frac{\tan k_2 L}{k_2} \right)^{-1} , \quad (42)$$

$$\frac{u_1}{u_5} = (k_1^2 - k_2^2)^{-1} \left[(k_2^2 - k_E^2) - \epsilon_{23} \Gamma \frac{u_6}{u_5} \right] \quad (43a)$$

$$\frac{u_2}{u_5} = (k_1^2 - k_2^2)^{-1} \left[-\mu \Gamma (k_2^2 - k_E^2) - \frac{\epsilon_{23}}{\epsilon_{22}} k_M^2 \frac{u_6}{u_5} \right] , \quad (43b)$$

$$\frac{u_3}{u_5} = (k_1^2 - k_2^2)^{-1} \left[-\frac{k_1^2 - k_E^2}{\epsilon_{23}} + \Gamma \frac{u_6}{u_5} \right] , \quad (43c)$$

$$\frac{u_4}{u_5} = (k_1^2 - k_2^2)^{-1} \left[\mu \Gamma \frac{k_1^2 - k_E^2}{\epsilon_{23}} + \frac{k_M^2}{\epsilon_{22}} \frac{u_6}{u_5} \right]. \quad (43d)$$

In the limit of small ϵ_{23} , equations (34a, b, c) show that u_6 , u_3 , and u_4 all approach zero, giving a pure TE mode for which $k_1^2 \rightarrow k_E^2$.

2.5 Transverse Magnetic-like Modes

Analogously, TM-like modes are the solutions of equation (40) for which

$$\frac{k_M^2}{\Gamma \epsilon_{22}} \frac{\tan k_2 L}{k_2} \sim 1. \quad (44)$$

For these modes, we solve for the u_i in terms of u_6 to get

$$\frac{u_5}{u_6} = \epsilon_{23} (k_2^2 - k_E^2)^{-1} \left[\Gamma - \frac{k_M^2}{\epsilon_{22}} \frac{\tan k_1 L}{k_1} \right] \left[1 + \mu \Gamma \frac{\tan k_1 L}{k_1} \right]^{-1}. \quad (45)$$

Then u_i/u_6 for $1 \leq i \leq 4$ are given by equations (43a, b, c, d) when formally multiplied by u_5/u_6 . In this case, in the limit of vanishing ϵ_{23} , equations (45) and (43a, b) show that u_5 , u_1 , and u_2 approach zero, giving a pure TM mode.

Since we consider cases for which $\epsilon_{11} > \epsilon_{33}$ (see discussion following eq (21a, b, c, d)), there may be solutions for which $k_M^2 > 0$, but $k_E^2 < 0$ if $\mu \epsilon_{33} k_O^2 \leq k_Y^2 \leq \mu \epsilon_{11} k_O^2$. In these regions, $k_2^2 > 0$ and $k_1^2 < 0$, in which cases $k_1 = -i|k_1|$ is taken with

$$\frac{\tan k_1 L}{k_1} = \frac{\tanh(|k_1| L)}{|k_1|}. \quad (46)$$

Thus, TM-like modes may appear for thickness L where TE-like modes are below cutoff. For pure imaginary k_1 , no solutions for equation (41) are possible; thus, no TE-like modes are possible for these values of k_Y^2 .

3. RESULTS

Calculations were performed to determine the Poynting vector, S_y , in the direction of propagation and the various field components associated with the lowest order modes. The ordinary and extraordinary indices of refraction were taken as $n_o = 2.34$ and $n_e = 2.24$, respectively, which correspond to 0.53- μm radiation ($\lambda_o = 0.53 \times 10^{-4}$ cm) in LiNbO_3 at 25 C. The equations scale, so that the results are identical for constant λ_o/L , where λ_o is the free space wavelength of the radiation. Several angles (θ_o) were chosen for the orientation of the dielectric axes with respect to the direction of propagation, which was kept fixed along the y-axis as shown in figure 1. The angle θ_o affects the parameters ϵ_{ij} according to equations (21a to d), for which $\epsilon_1 = \epsilon_2 = n_o^2 = 5.4756$ and $\epsilon_3 = n_e^2 = 5.0176$.

For small angles of propagation of about $\theta_o = 5$ deg or less, the results are essentially the same as for $\theta_o = 0$ deg in which case the axes are collinear. For $\theta_o = 0$ deg, the fundamental TE and TM modes for $\lambda_o/L = 0.53$ are shown in figures 2 and 3. Although the total power flows are not normalized, one can distinguish that

a. The TE mode (fig. 2) has only one component of the E-field that is along the dielectric z-axis parallel to the surface of the slab.

b. This mode "sees" predominantly n_e , except for the energy in free space; hence, the effective index of refraction, n_{eff} , is slightly less than n_e : $n_{\text{eff}} = 2.22553$.

c. The TM mode (fig. 3) has two components of E, one perpendicular to the surface of the slab and one parallel to the surface along the direction of propagation (y).

d. This mode "sees" predominantly n_o , except for the energy in free space; hence, n_{eff} is slightly less than n_o : $n_{\text{eff}} = 2.3363$.

e. The power flow of the TE mode is closer to the surface of the slab, and a greater percentage of its energy is contained in free space. In contrast, the power flow of the TM mode is closer to the conductor.

f. The magnitude of E_y in the TM mode relative to E_x gets larger as the surface is approached from within the dielectric. (This property may be significant in understanding the interaction of these waves with SAW's.)

The modes depicted in figures 2 and 3 can be labeled the TE_0 and TM_0 modes in which, in general, TE_m and TM_m modes have m changes in sign in their E_z and H_z components, respectively. As L increases, the relatively little change in the form of the modes indicates that, within a fixed distance from the surface of the dielectric, there is proportionately less fractional power of the total flowing in the dielectric. For the higher order modes, m large, a larger amount of power is in the free space near the surface. As m grows larger, $n_{eff} \rightarrow 1$, $k_y^2 \rightarrow k_0^2$, and $\Gamma \rightarrow 0$; thus, the damping of the evanescent portion of the wave in free space is less severe.

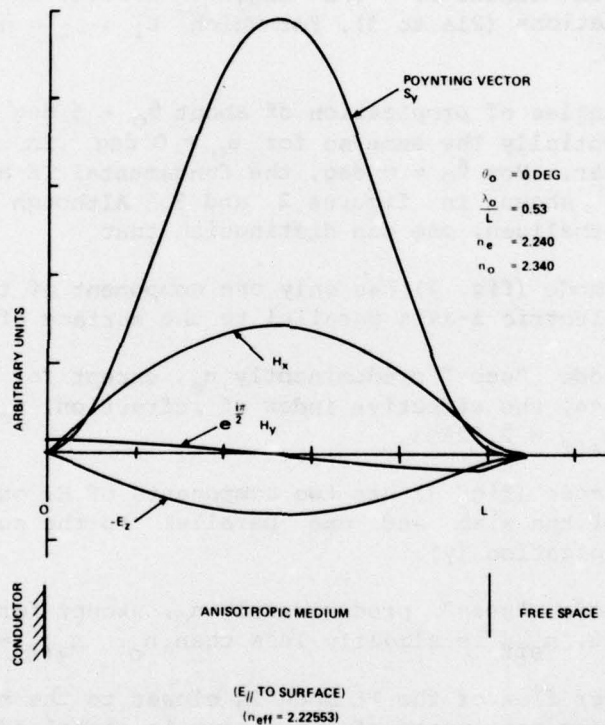


Figure 2. Electromagnetic field components for fundamental transverse electric (TE_0) mode in slab of thickness $L = \lambda_0/0.53$ for $\theta_0 = 0$ deg angle of propagation.

The variation of n_{eff} of the TE_0 mode for different L as a function of θ_0 is shown in figure 4. The thickness L_m corresponds to an "m" μm thickness slab for $\lambda_0 = 0.53 \mu\text{m}$ (green) radiation; thus, the infinite medium case is rapidly approached by small thicknesses. For practical thicknesses ($\sim 1/8$ in. ~ 0.3 cm), laser radiation incident as a sheet beam over the surface of the dielectric excites a very large number of higher order modes. The variation of the field components near the surface, however, is very much like the variations near the surface depicted in figures 2 and 3.

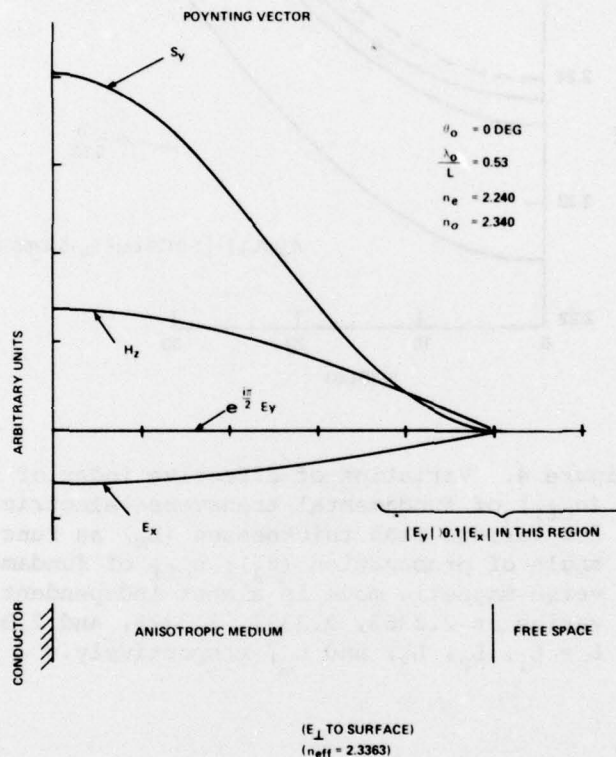


Figure 3. Electromagnetic field components for fundamental transverse magnetic (TM_0) mode in slab of thickness $L = \lambda_0/0.53$ for $\theta_0 = 0$ deg angle of propagation.

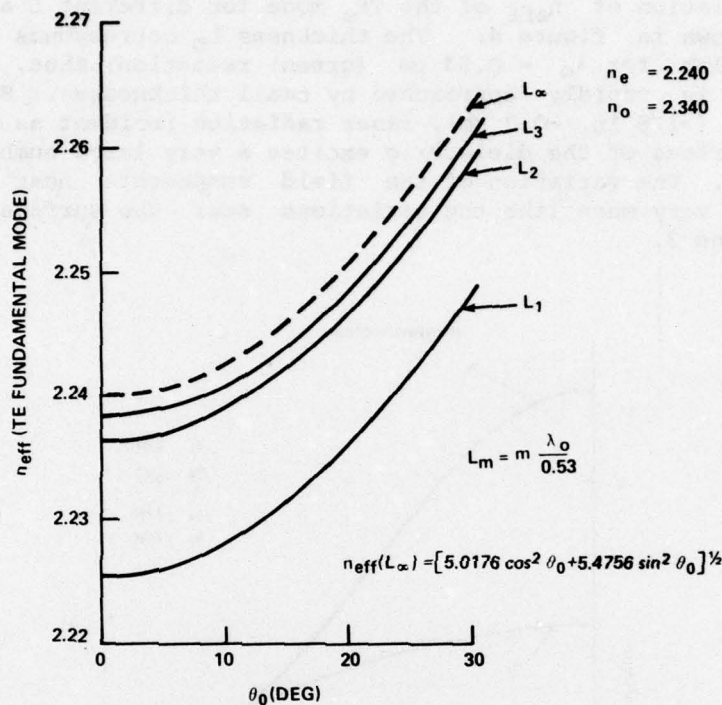


Figure 4. Variation of effective index of refraction (n_{eff}) of fundamental transverse electric (TE) mode for various slab thicknesses (L_m) as function of angle of propagation (θ_0); n_{eff} of fundamental transverse magnetic mode is almost independent of θ_0 and varies as 2.3363, 2.3391, 2.3396, and 2.340 for $L = L_1, L_2, L_3$, and L_∞ , respectively.

Figure 5 shows a typical higher order mode propagating at an angle of $\theta_0 = 19$ deg. This is a TM_2 -like mode (two zero crossings for H_z), which shows the relative amounts of H_x , H_y , and E_z components generated at this angle. These components are absent in TM modes propagating at the $\theta_0 = 0$ deg angle. The discontinuity in E_x at the surface is clearer in this higher order mode than in the TM_0 mode in figure 3.

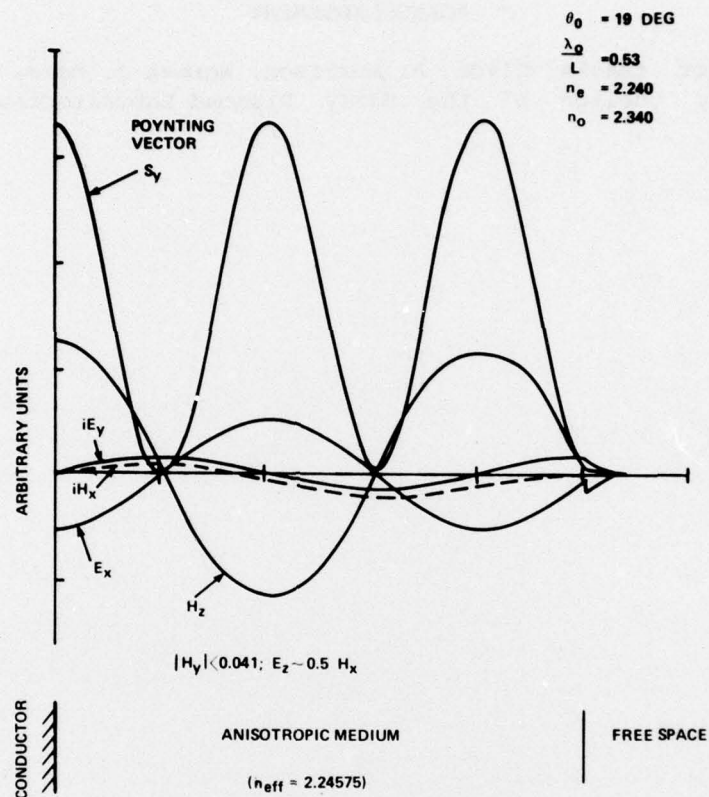


Figure 5. Electromagnetic field components for transverse magnetic (TM_2)-like mode in slab of thickness $L = \lambda_0/0.53$ for $\theta_0 = 19$ deg angle of propagation.

4. CONCLUSIONS

These calculations show that many TE and TM modes are allowed in slabs of practical thicknesses. The problem of forming linear combinations of these modes to approximate a sheet laser beam propagating near the surfaces of thick slabs is, accordingly, formidable. What is necessary for a qualitative understanding of the interaction between such sheet beams and SAW's may be clear, however, from the examples given here. If further work is necessary for a more quantitative picture, the formalism derived here and the computer programs developed in this connection are available from the author.

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